

Malware Detection under Concept Drift: Science and Engineering

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Whoami

Education

- Assistant Professor @ TAMU (Since 2022)
- CS PhD @ UFPR, Brazil (2021)
- CSE/ECE BSc. + CS MSC @ UNICAMP, Brazil (2015, 2017)

Research

- **Malware** at high-level: ML-based detectors.
- **Malware** at mid-level: Sandboxes and tracers.
- **Malware** at low-level: HW-based detectors.

Current Project

- NSF SaTC: Hardware Performance Counters as the next-gen AVs.

Publication

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Towards Explainable Drift Detection and Early Retrain in ML-Based Malware Detection Pipelines

Conference paper | First Online: 10 July 2025

pp 3–24 | [Cite this conference paper](#)

Figure: Source: https://link.springer.com/chapter/10.1007/978-3-031-97623-0_1

Agenda

- 1 Concept Drift
 - It is a long-term trend
 - The trend is in the data
- 2 Understanding Drift
 - Classes are affected differently
 - Our theory of drift events
- 3 Testing the Hypothesis
 - How to monitor drift events
 - The results do make sense
- 4 Demonstration
 - Explaining events by examples
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 - Performance Drawbacks
 - Labeling Issues
- 6 Engineering Solutions
- 7 Conclusions
 - Closing Remarks

It is a long-term trend

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It is a long-term trend

It is a long-term trend

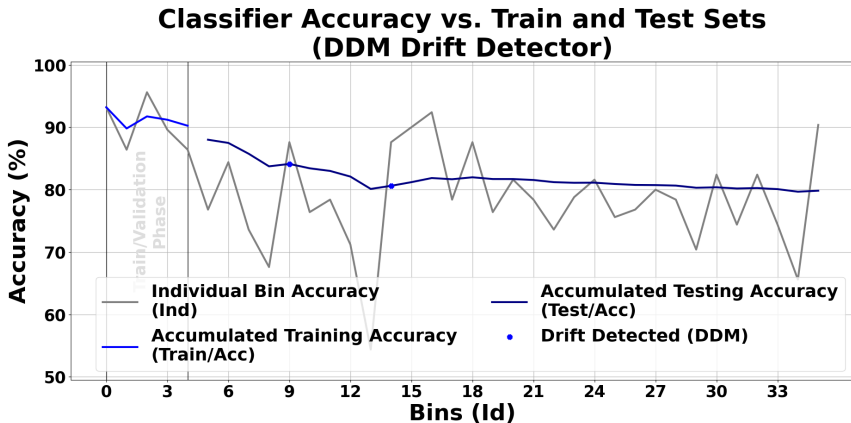


Figure: Drift tendency vs. instantaneous detection. Drift points reported by ADWIN.

The trend is in the data

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The trend is in the data

You increase the training size, but the drift is always there!

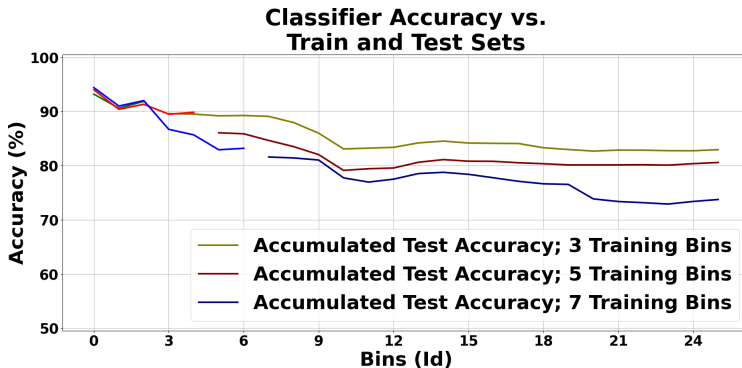


Figure: Concept drift in practice. The classification accuracy decreases regardless of the initial training set size/period.

The trend is in the data

You change the policy, but the drift is always there!

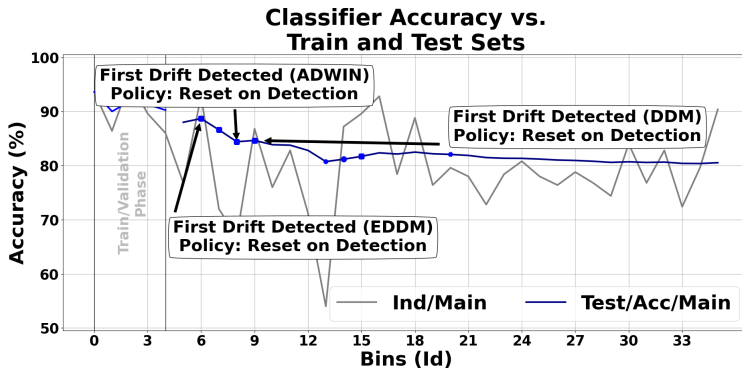


Figure: Comparing algorithms and policies. Each one detects a different number of drift points/events and at different times.

Classes are affected differently

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Classes are affected differently

Classes are affected differently

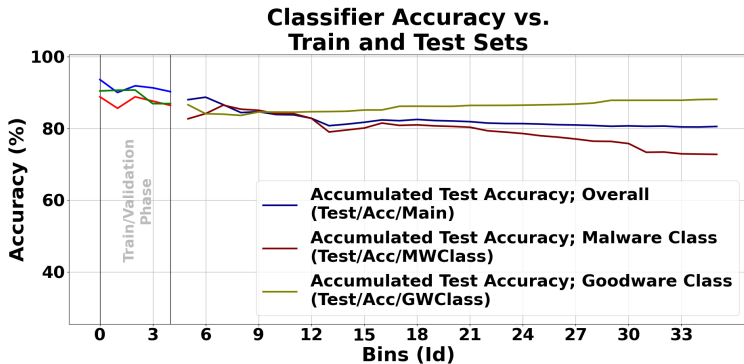


Figure: Separating detection rates per class reveals that the drift in the MW class causes the global performance degradation.

Classes are affected differently

Classes drift differently

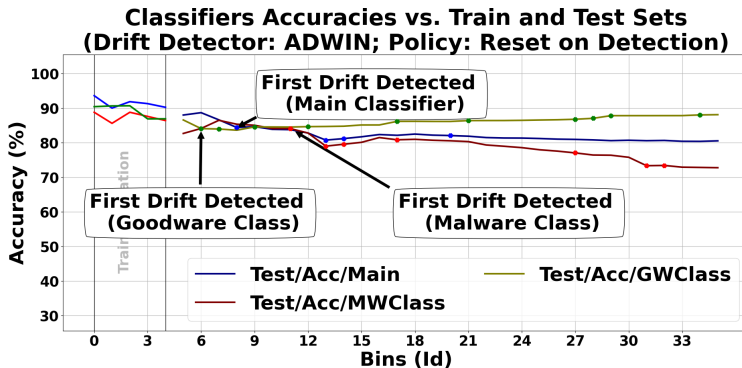


Figure: Main class vs. sub-classes. A different number of drift points is identified in each class and at different epochs.

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Our theory of drift events

Key Hypothesis: Concepts and Frontiers are different things

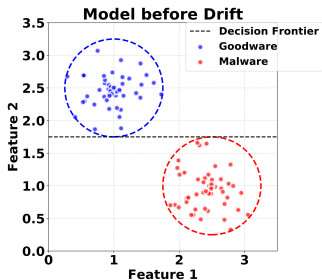


Figure: Initial Training.

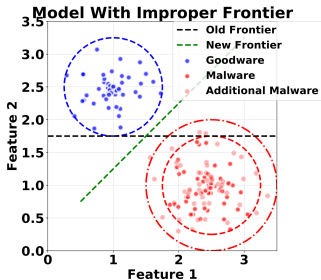


Figure: Additional Data.

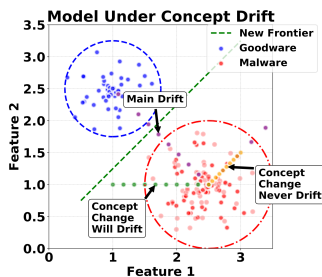


Figure: Multiple Drifts.

Proposing a drift taxonomy (1/2)

- **Type 1:** Main Classifier Drift. It detects whether a significant number of samples of any class crossed the detection frontier or not within a sampling window to the point of already harming the final classification result.
- **Type 2:** Sub-Class Drift. It detects whether a significant number of samples of a specific class crossed the detection frontier or not within a sampling window to the point of being noticeable but without guarantees that it affects the final classification result (contingent upon Type 1 detection).
- **Type 3:** Concept Change. It detects if a significant number of samples of a specific class do not match the previous knowledge the classifier had about that class, regardless of the correct class assignment (Type 1 and 2 events).

The concept evolution direction matters

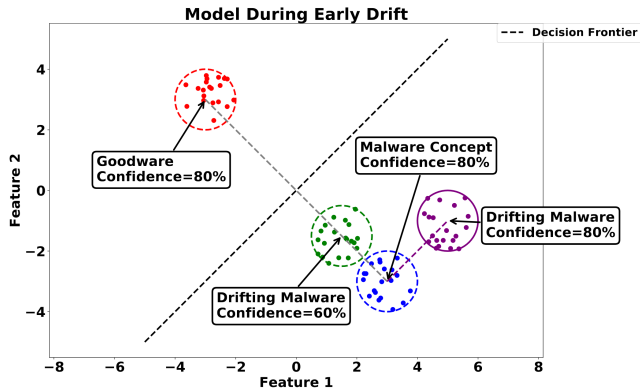


Figure: Direction-Change Drift Detection.

Proposing a drift taxonomy (2/2)

- **Type 3: Concept Change.** It detects if a significant number of samples of a specific class do not match the previous knowledge the classifier had about that class, regardless of the correct class assignment (Type 1 and 2 events). The implications of the concept change causing drift or not are contingent on the following cases:
 - **Case A: Concept change without drift risk.** If the concept changes in a direction that does not go toward the decision frontier, it cannot cause drift events.
 - **Case B: Concept change with imminent drift risk.** If the concept changes towards the decision frontier (Type 2), it will eventually cause drift when crossing the frontier (Type 1). This point is a candidate for early retraining.
 - **Case C: Current Drift due to concept change.** If the concept changes towards the frontier (Type 2) and crosses it (Type 1), concept drift is detected late.

The final drift taxonomy

Table: Explaining Drift Events. Information types for each combination of triggered detectors. Representing Triggered Detectors (✓) and Possible (△) and Not-Applicable (∅) cases. Omitting Impossible cases.

Main Type			Cases			Conclusion
Type 1	Type 2	Type 3	Case A	Case B	Case C	
				∅		Normal Operation
		✓	△			Early Concept Change with no impact on frontier
		✓		△		Early Concept Change with imminent impact on frontier
	✓			∅		Bad Frontier detected without concept change hold by imbalance in main class
	✓	✓		△		Bad Frontier detected with concept change hold by imbalance in main class
✓				∅		False Positive Drift Detection
✓		✓	△			False Positive with concept change in non-impactful direction
✓	✓			∅		Bad Frontier detected without concept change, with impact in the main class
✓	✓	✓			△	Concept Change with Immediate Impact and Identification

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How to monitor drift events

Agnostic model monitor with external meta-models

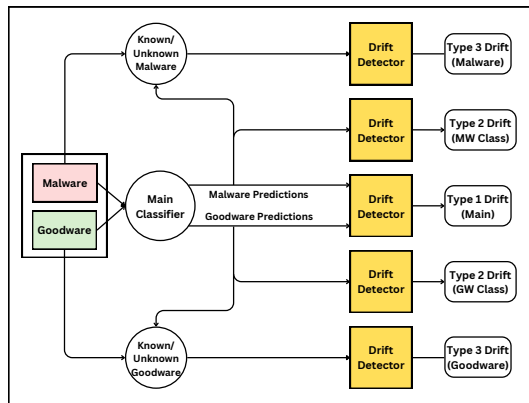


Figure: Drift-Explainable Architecture.

The results do make sense

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The results do make sense

The concept classes indeed measure different things

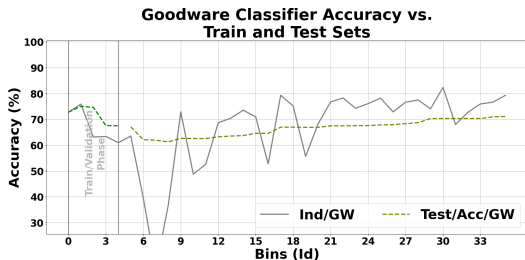


Figure: GW class self-recognition rate.

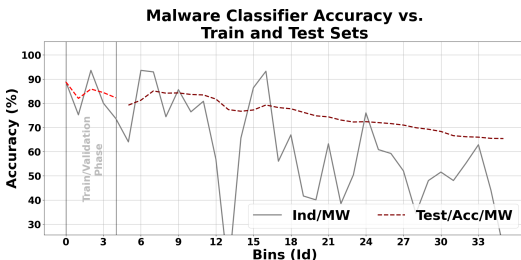


Figure: MW class self-recognition rate.

The results do make sense

The concept classes indeed drift

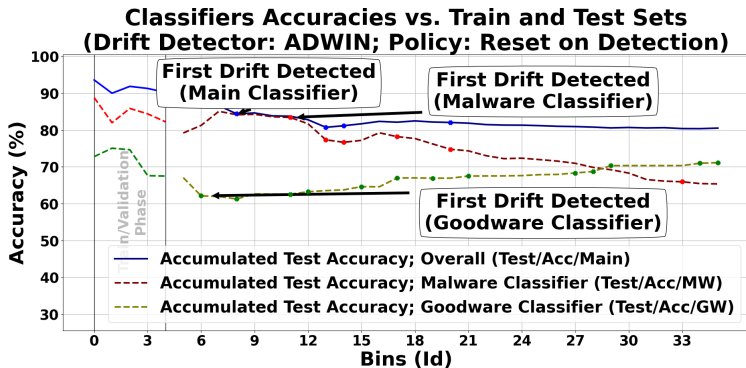


Figure: Drift in the classes self-recognition rates. Drifts are represented both for the MW and GW meta-classifiers.

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Explaining events by examples

Every point can be explained.

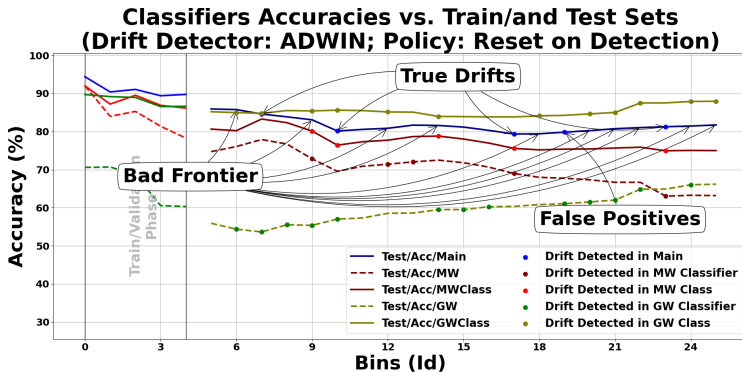


Figure: Explaining all operational points and all drift occurrences. Omitting points of normal operation.

The effect of dataset imbalance is also explained.

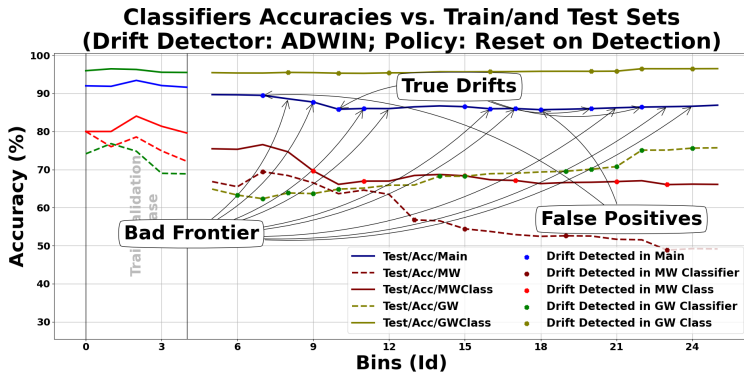


Figure: Explaining all drift detection points (2:1 balance). We observe fewer frontier problems and more False Positives.

Calibrating drift detectors is essential

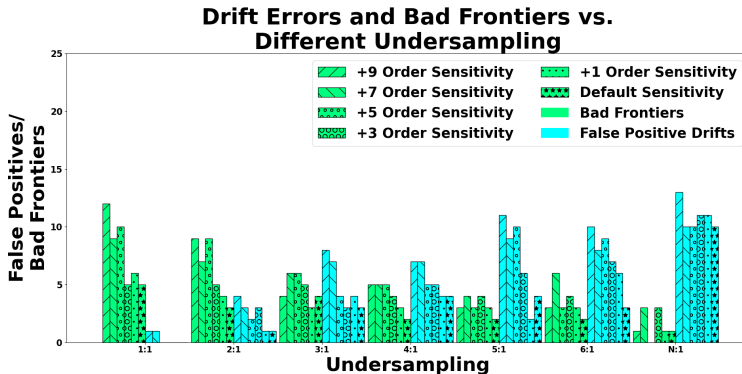


Figure: Drift Detector Calibration. False Positives and bad frontiers are explained by the proposed approach.

Explaining events by examples

Explaining concepts lead to better accuracies via early retrain

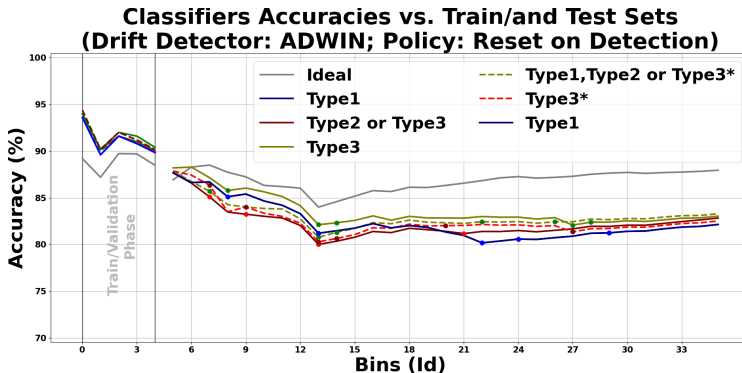


Figure: Early retraining on concept changes leads to improved accuracy than retraining only upon main class drift.

Early retrain is more effective

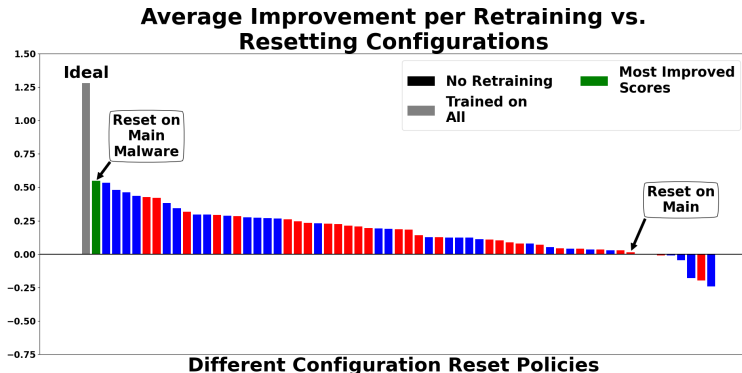


Figure: Retrain Effectiveness. The vast majority of the proposed drift detection triggers lead to increased accuracy gains than the original Type 1 drift detector trigger.

Explaining events by examples

Early retrain is more efficient

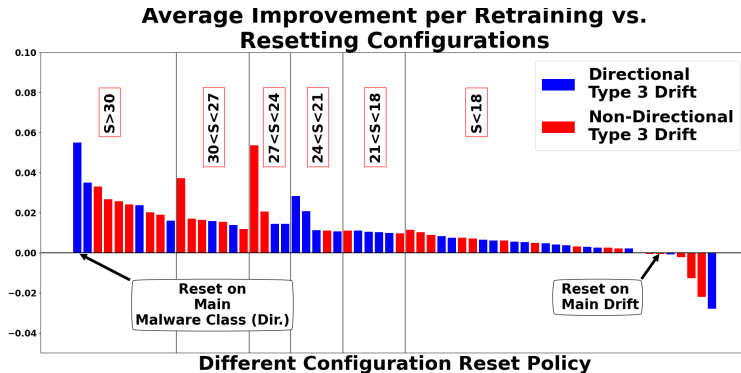


Figure: Retrain Efficiency. The best cost-benefit between the amount of retrains and accuracy increase is achieved by identifying concept changes.

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False Positives always increase with imbalances

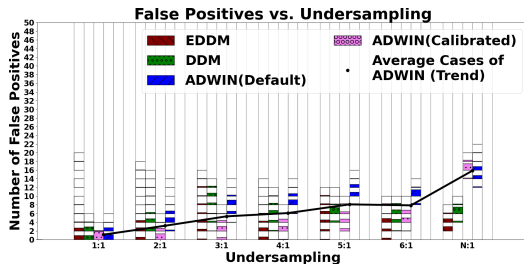


Figure: DREBIN: FP Results Distribution for different imbalances. FPs grow with the imbalance for most detectors.

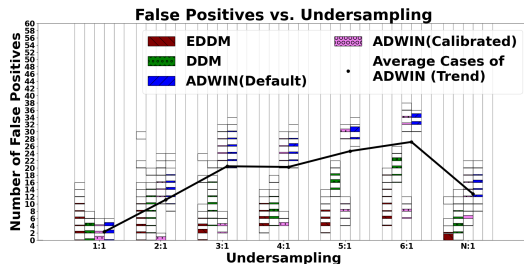


Figure: ANDROZOO: FP Results Distribution for different imbalances. FPs grow with the imbalance for most detectors.

Bad Frontiers always decrease with imbalances

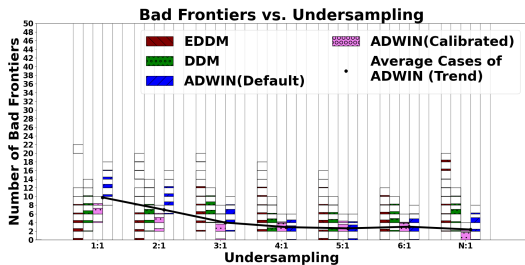


Figure: DREBIN: Detectors' Results Distribution. Frontier problems for different undersamplings. The bigger the undersampling, the more frontier problems.

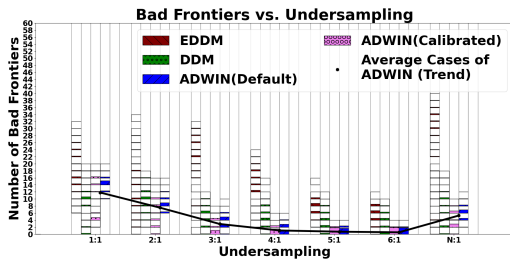


Figure: ANDROZOO: Detectors' Results Distribution. Frontier problems for different undersamplings. The bigger the undersampling, the more frontier problems.

Early retrain is always the best option

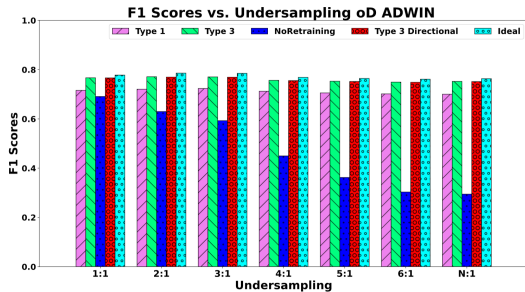


Figure: DREBIN: Average Retraining Results. Average F1-score Under Time increase over the baseline when triggering retraining using different policies vs. the multiple dataset imbalances.

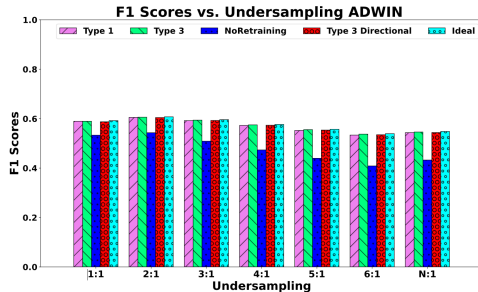


Figure: ANDROZOO: Average Retraining Results. The imbalance effect is less pronounced in this dataset, but the Type-3 retraining strategy is still the superior one in all scenarios.

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Explanation comes at the performance cost

Table: Runtime Performance Overhead for DREBIN and AndroZoo. The cost of individual retrains is reduced, but the total execution time cost increases.

Models (#)	Retrain Policy	DREBIN		AndroZoo	
		Total Time / Retrains (#)	Cost / Overhead / Normalized	Total Time / Retrains (#)	Cost / Overhead / Normalized
1	Type 1	11.65s / 5	2.73s / 0x / 0x	470.4s / 5	94s / 0x / 0x
3	Type 1	53.53s / 5	10.7s / 3.92x / 3.92x	1688.6 / 5	337.7s / 3.6x / 3.6x
3	Type 2	105.77s / 13	8.13s / 7.74x / 2.98x	3563.9s / 15	237.6s / 7.5x / 2.5x
3	Type 3	102.70s / 13	7.90s / 7.52x / 2.89x	4161.3s / 19	219s / 8.84x / 2.32x

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Limitations & Future Works

- Heterogeneous Architectures.
- Virtual Drifts.
- Intra-Class Drifts.
- **Label Delays.**

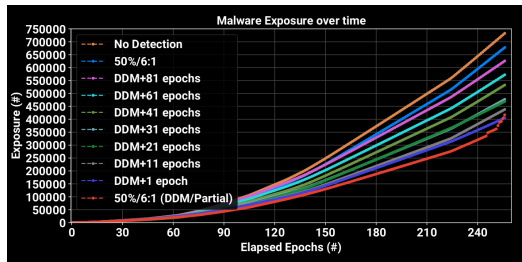


Figure: Label Delays. Too much delay nullifies the retraining benefits.

Publications



Figure: Source:

<https://www.sciencedirect.com/science/article/abs/pii/S0167404824004279>

How to Evaluate the Classification Impact?

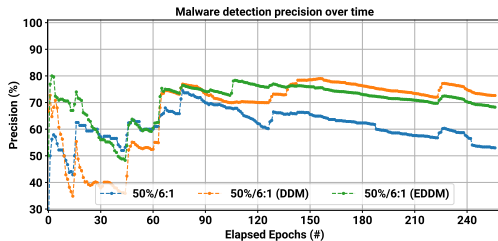


Figure: Classification Precision.

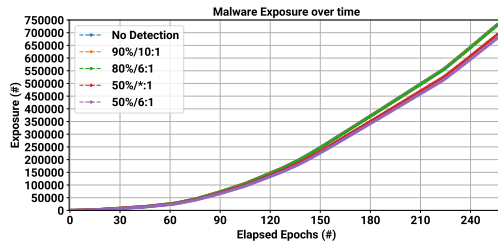


Figure: Absolute Exposure.

How to Evaluate the Drift Impact?

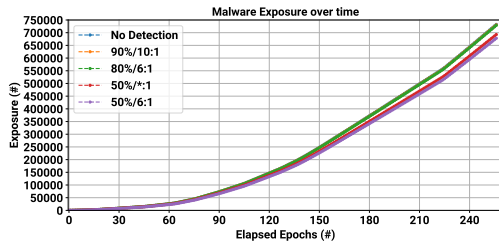


Figure: Absolute Exposure.

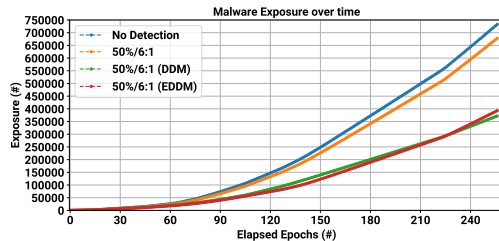


Figure: Absolute Exposure and Drift.

What if Labels are not available?

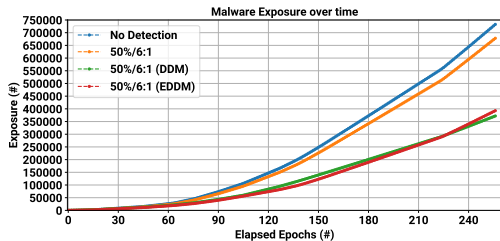


Figure: Absolute Exposure and Drift.

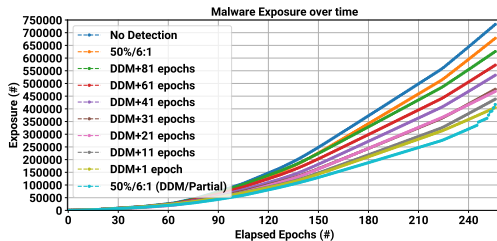


Figure: Delayed ground-truth labels.

The Pseudo-Label Delay Mitigation

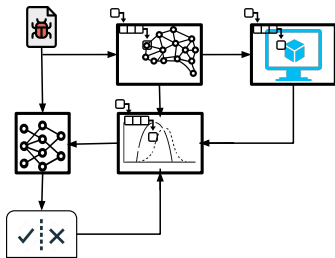


Figure: Architecture with Pseudo-Labels.

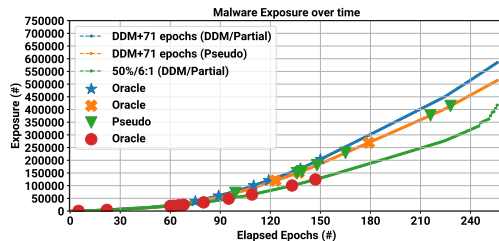


Figure: New Drift Points.

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Recap

Science

- Explaining drift is not the same as explaining the classification.
- Classifier concept and frontier are not the same thing.
- Meta-classifiers can separate concepts and frontiers.
- We can explain every drift event.

Engineering

- Labels are not immediately available.
- Too long delays eliminate the benefits of classifier retrain.
- Pseudo-Labels mitigate label delays.

Thanks!

Questions? Comments?

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